Lecture 1: Introduction and Vertex Cover

Part I: Organizational

Lectures: on site (in German :-)

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Fri, 10:15-11:45 (ÜR I)

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Bonus (+0.3 on final grade) for $\geq 50\%$ points

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Questions/Tasks during the lecture

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Tutorials: roughly one exercise sheet per lecture

discussing old solutions and solving new tasks

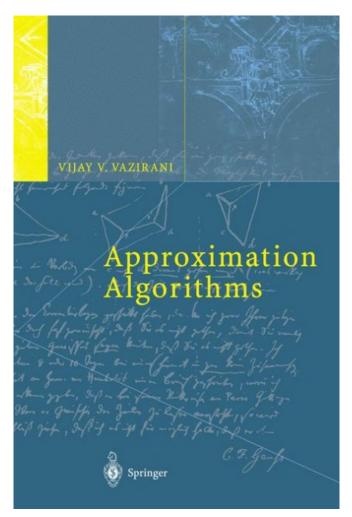
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Questions/Tasks during the lecture

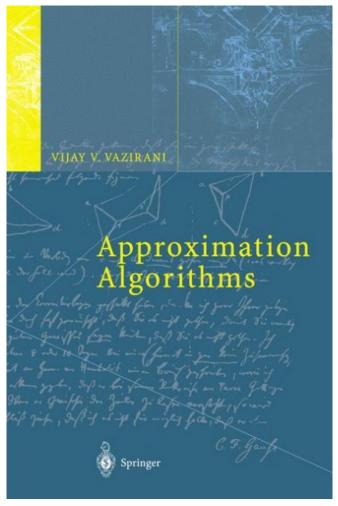
Most slides are due to Joachim Spoerhase. Thanks!

Textbooks

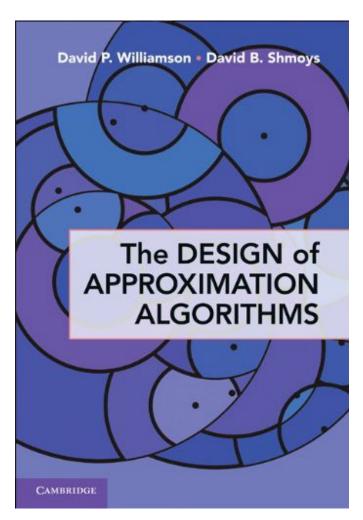


Vijay V. Vazirani: Approximation Algorithms Springer-Verlag, 2003.

Textbooks



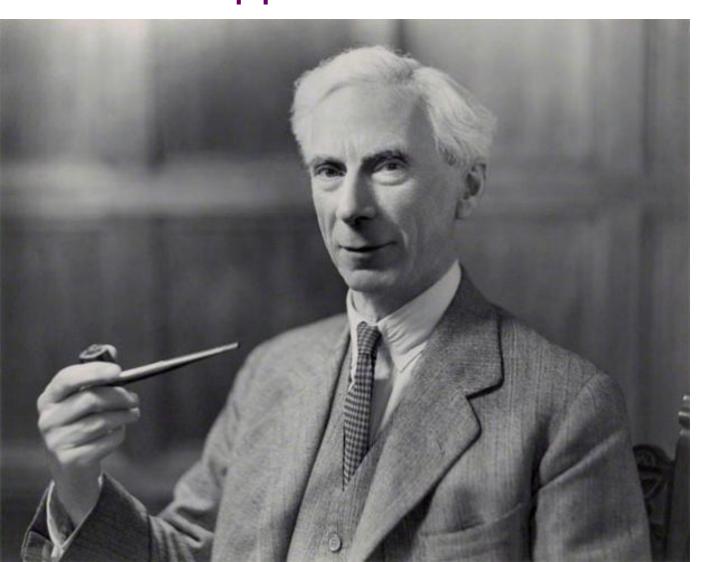
Vijay V. Vazirani: Approximation Algorithms Springer-Verlag, 2003.



D. P. Williamson & D. B. Shmoys: The Design of Approximation Algorithms Cambridge-Verlag, 2011.

http://www.designofapproxalgs.com/

"All exact science is dominated by the idea of approximation."



Bertrand Russell(1872 – 1970)

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 (For example, the traveling salesperson problem.)
- an optimal solution cannot be efficiently computed unless P=NP.
- However, good approximate solutions can often be found efficiently!
- Techniques for the design and analysis of approximation algorithms arise from studying specific optimization problems.

Overview

Combinatorial algorithms

- Introduction (Vertex Cover)
- Set Cover via Greedy
- Shortest Superstring via reduction to SC
- Steiner Tree via MST
- Multiway Cut via Greedy
- *k*-Center via Parametrized Pruning
- Min-Degree Spanning Tree and local search
- Knapsack via DP and Scaling
- Euclidean TSP via Quadtrees

Overview

Combinatorial algorithms

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LP-based algorithms

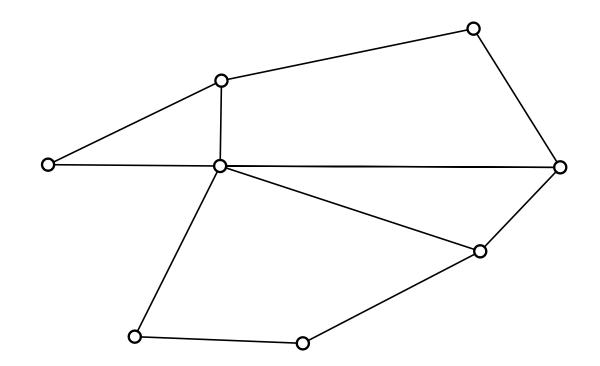
- introduction to LP-Duality
- Set Cover via LP Rounding
- Set Cover via Primal–Dual Schema
- Maximum Satisfiability
- Scheduling und Extreme Point Solutions
- Steiner Forest via Primal–Dual

Lecture 1: Introduction and Vertex Cover

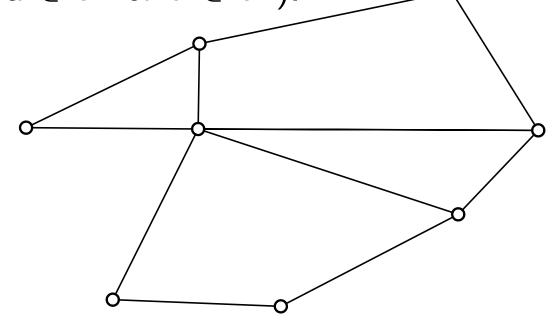
Part II: (Cardinality) Vertex Cover

Input: Graph G = (V, E)

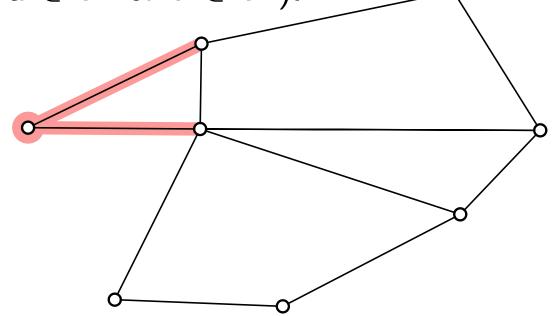
Output:



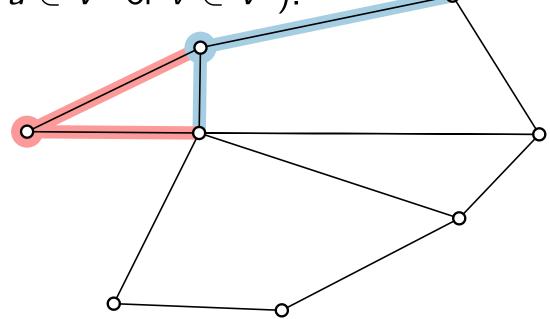
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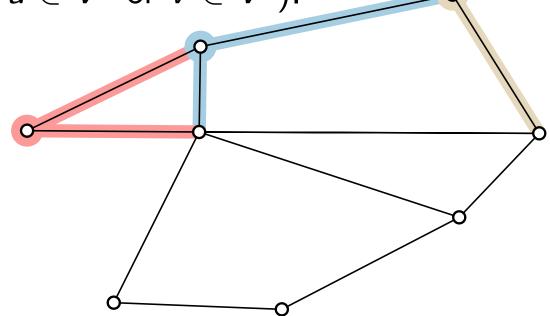
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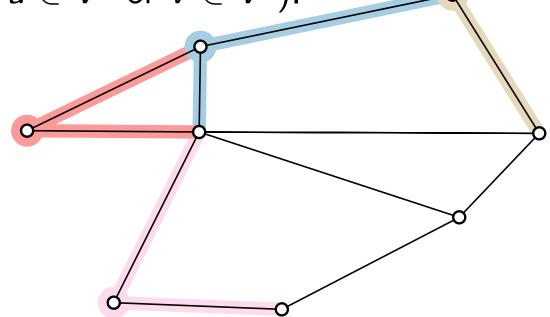
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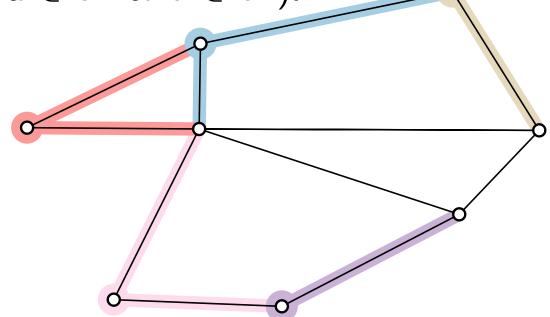
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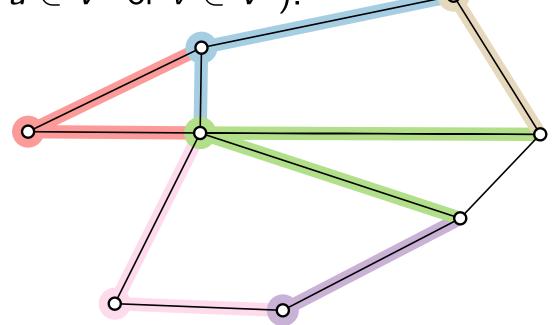
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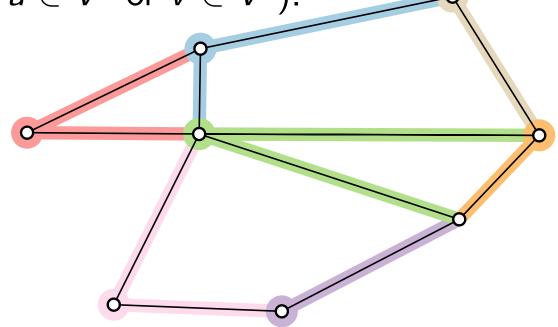
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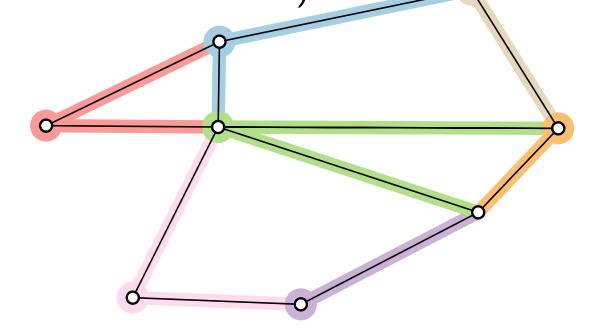
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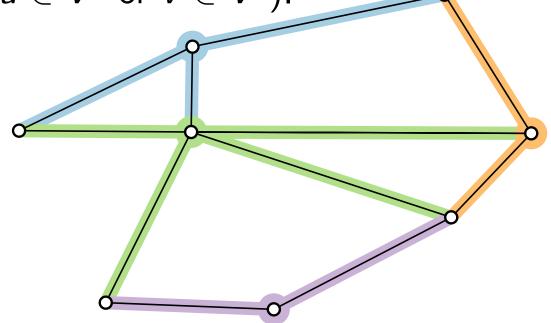
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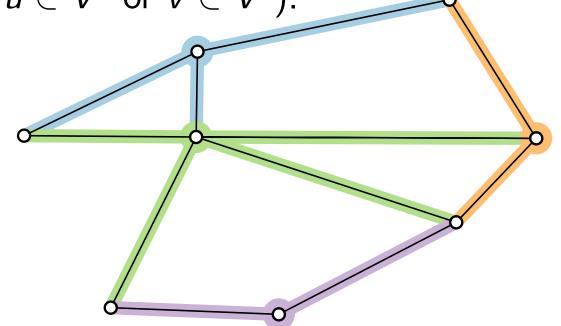
Output: a minimum **vertex cover**, that is, a minimum-cardinality vertex set $V' \subseteq V$ such that every edge is **covered** (i.e., for every $uv \in E$, it holds that $u \in V'$ or $v \in V'$).



Optimum (OPT = 4)

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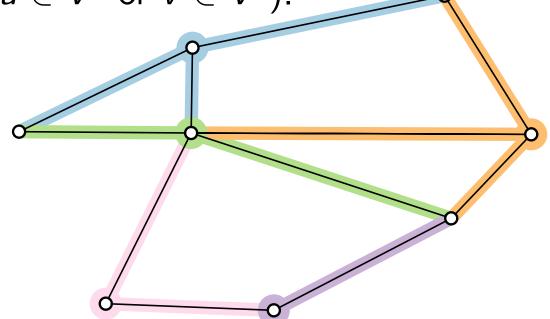
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Optimum (OPT = 4) – but in general NP-hard to find :-(

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"good" (5/4-) approximate solution

Lecture 1: Introduction and Vertex Cover

Part III: NP-Optimization Problem

An NP-optimization problem Π is given by:

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- \blacksquare Π is either a minimization or maximization problem.

Task: Fill in the gaps for $\Pi = VERTEX COVER$.

$$D_{\Pi}=$$
For $I\in D_{\Pi}$: $|I|=$
 $S_{\Pi}(I)=$

- Why is $|s| \in \text{poly}(|I|)$ for every $s \in S_{\Pi}(I)$?
- For a given pair (s, I), how can we efficiently decide whether $s \in S_{\Pi}(I)$?

$$\operatorname{obj}_{\Pi}(I,s) =$$

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Let Π be a minimization problem and $I \in D_{\Pi}$ an instance of Π .

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A feasible solution $s^* \in S_{\Pi}(I)$ is **optimal** if $\operatorname{obj}_{\Pi}(I, s^*)$ is minimal among the objective values attained by the feasible solutions of I.

maximization problem Let Π be a minimization problem and $I \in D_{\Pi}$ an instance of Π .

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A feasible solution $s^* \in S_{\Pi}(I)$ is **optimal** if $\underset{\Pi}{\text{obj}}_{\Pi}(I, s^*)$ is minimal among the objective values attained by the feasible solutions of I.

The optimal value $obj_{\Pi}(I, s^*)$ of the objective function is denoted by $OPT_{\Pi}(I)$ or simply by OPT in context.

Let Π be a minimization problem and $\alpha \in \mathbb{Q}^+$.

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$$\frac{\mathsf{obj}_{\Pi}(I,s)}{\mathsf{OPT}_{\Pi}(I)}$$

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$$\frac{\operatorname{obj}_{\Pi}(I,s)}{\operatorname{OPT}_{\Pi}(I)} \leq \alpha.$$

Let Π be a minimization problem and $\alpha: \mathbb{N} \to \mathbb{Q}$

$$\frac{\operatorname{obj}_{\Pi}(I,s)}{\operatorname{OPT}_{\Pi}(I)} \leq \mathscr{A}. \quad \alpha(|I|)$$

$$\frac{\mathsf{obj}_{\Pi}(I,s)}{\mathsf{OPT}_{\Pi}(I)} \stackrel{\geq}{\leq} \mathscr{A}. \quad \alpha(|I|)$$

Lecture 1: Introduction and Vertex Cover

Part IV:

Approximation Algorithm for VERTEXCOVER

Approximation Alg. for VERTEXCOVER

Ideas?

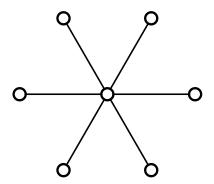
Edge-Greedy

Approximation Alg. for VERTEXCOVER

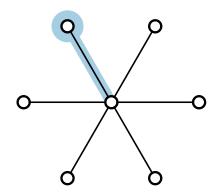
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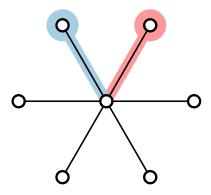
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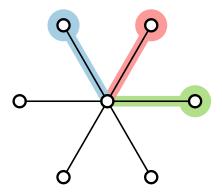
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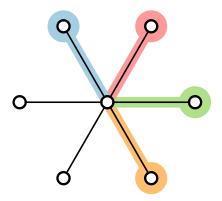
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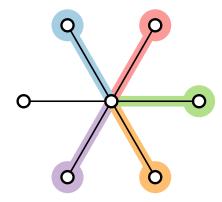


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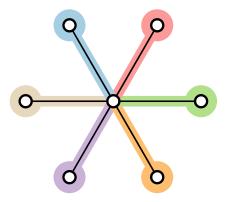
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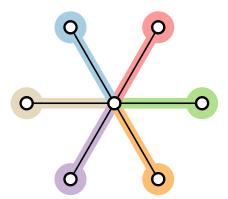
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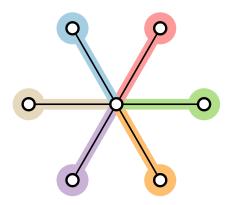
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Quality?

Ideas?

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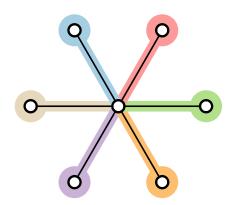


Quality?

Problem: How can we estimate $obj_{\Pi}(I, s)/OPT$, when it is hard to compute OPT?

Ideas?

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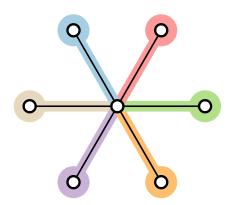
when it is hard to compute OPT?

Idea: Find a "good" lower bound $L \leq OPT$ for OPT and

compare it to our approximate solution.

Ideas?

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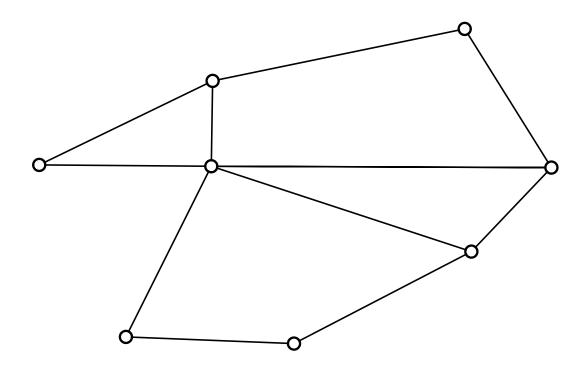
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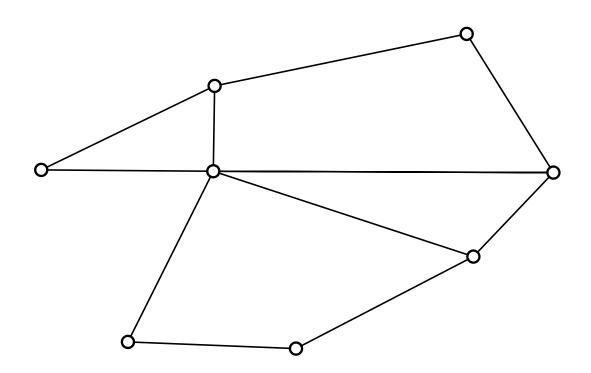
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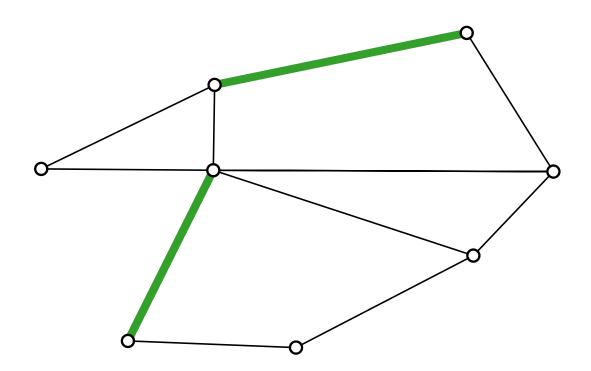
$$\frac{\operatorname{obj}_{\Pi}(I,s)}{\operatorname{OPT}} \leq \frac{\operatorname{obj}_{\Pi}(I,s)}{L}$$



An edge set $M \subseteq E$ of a graph G = (V, E) is a **matching** if no two edges of M are adjacent (i.e., share an end vertex).

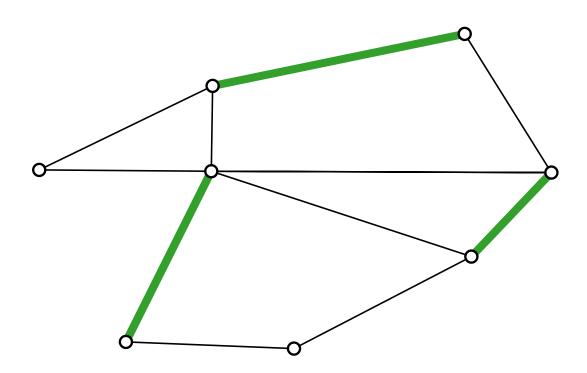


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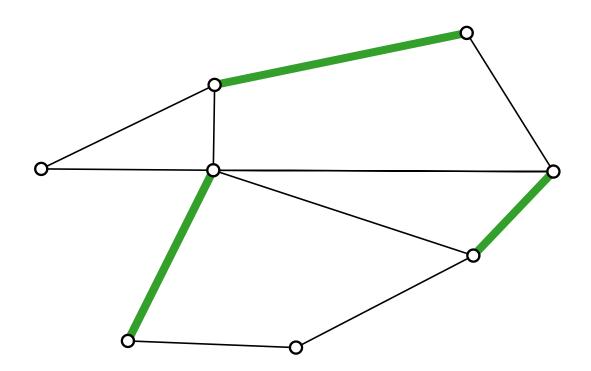
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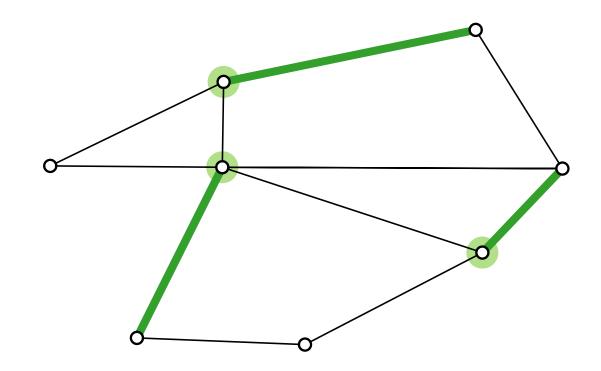
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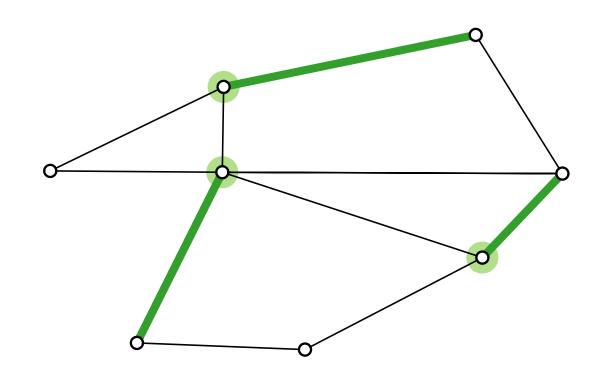
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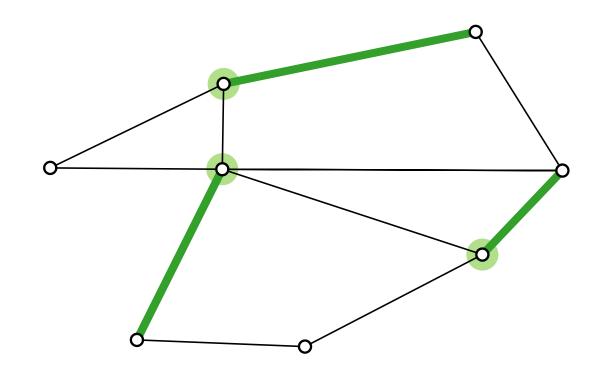


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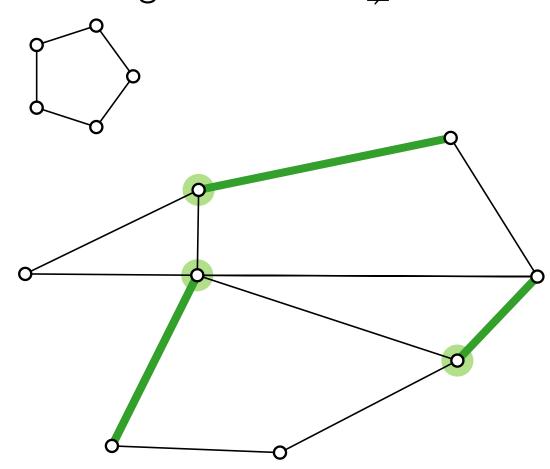


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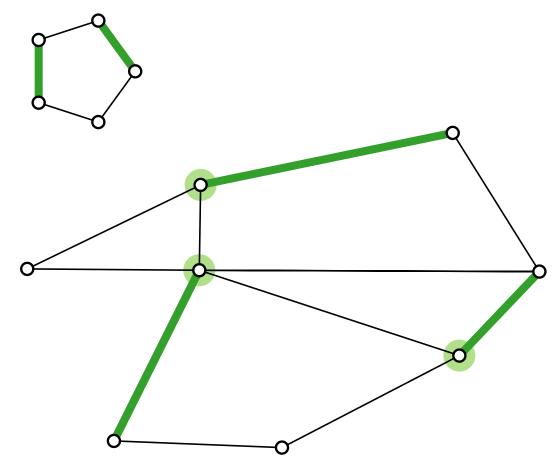


Given a graph G, a set M of edges of G is a **matching** if no two edges of M are adjacent (i.e., share an end vertex).

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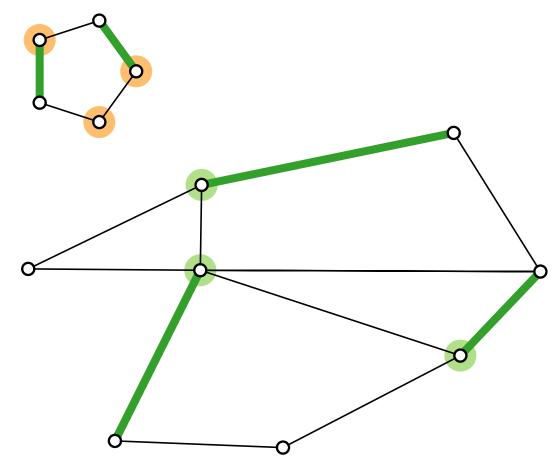


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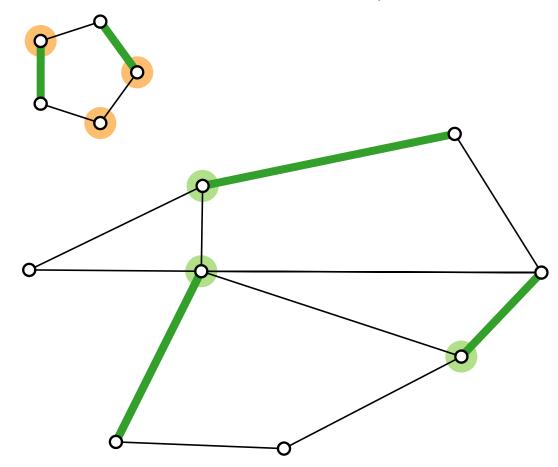
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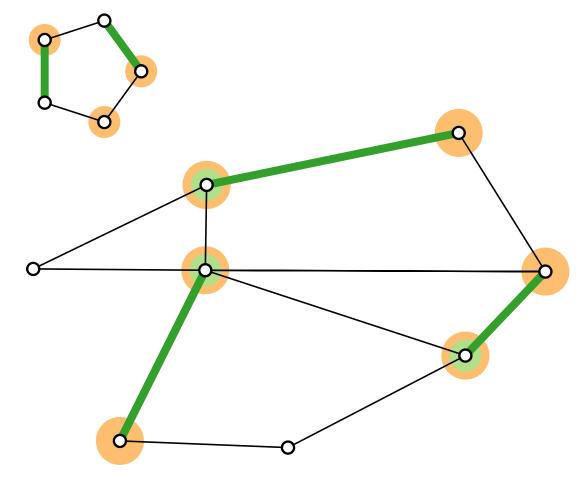
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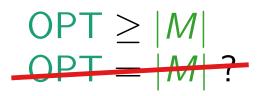
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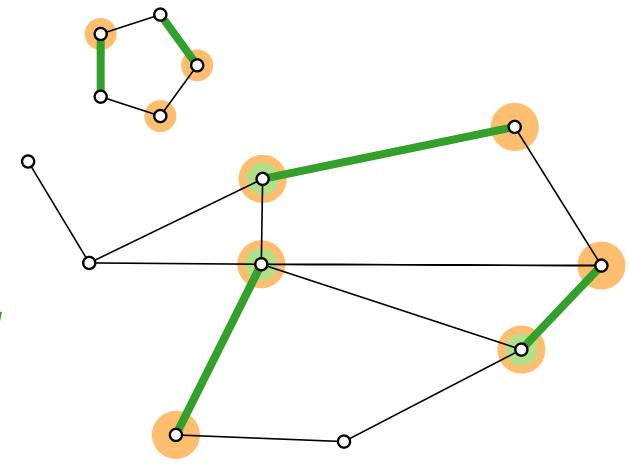
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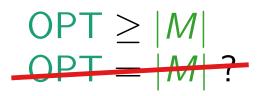
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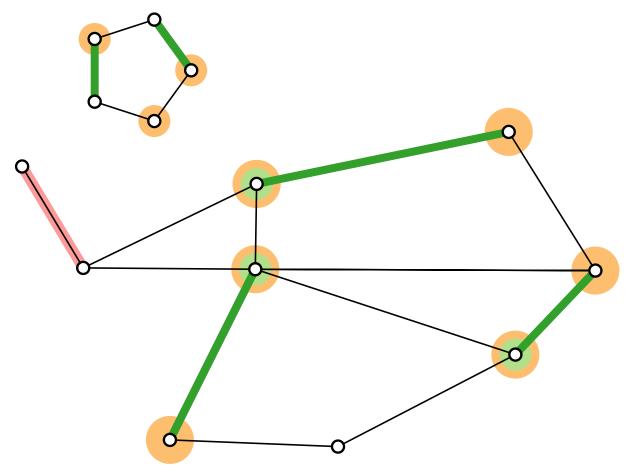




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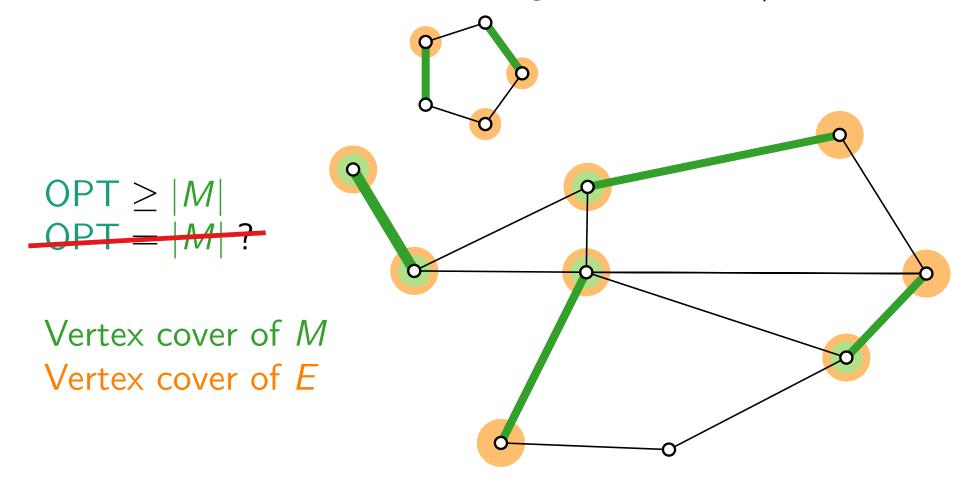
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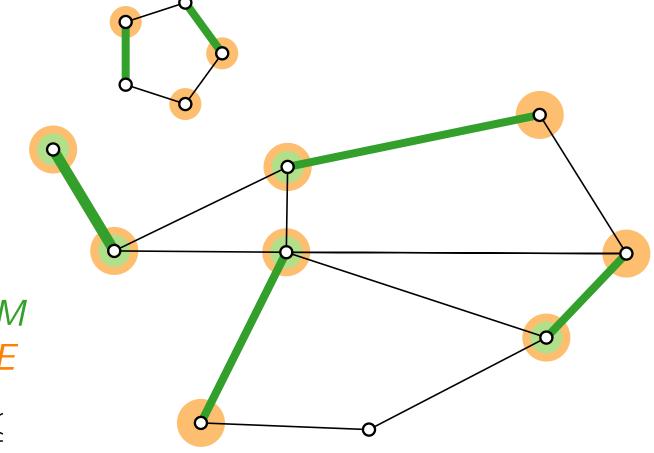
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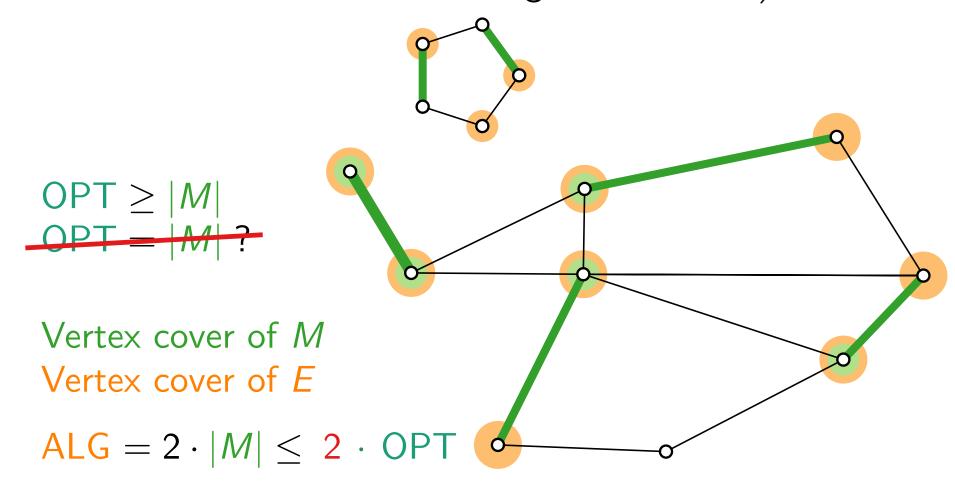


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$$ALG = 2 \cdot |M| \le$$

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Algorithm VertexCover(G)

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Approximation Alg. for VERTEXCOVER

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Theorem. The above algorithm is a factor-2 approximation algorithm for VERTEXCOVER.

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VERTEXCOVER cannot be approximated within a factor of $2 - \Theta(1)$ – if the *Unique Games Conjecture* holds.